



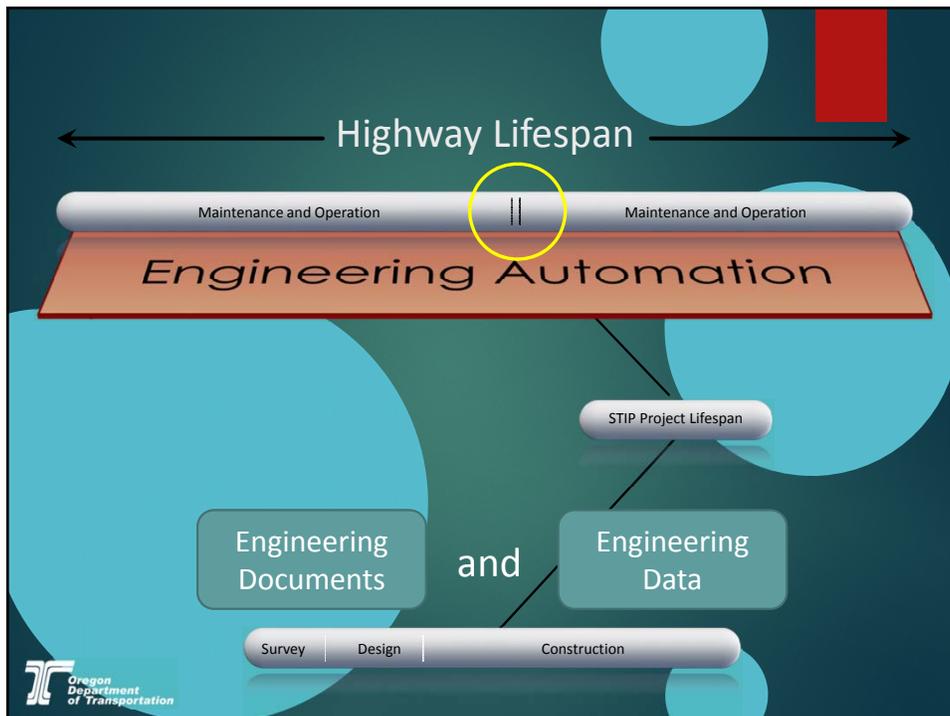
Engineering Automation At Oregon DOT

An Overview

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Engineering Automation Manager/Chief of Surveys

1 March, 2016



Engineering Automation





Engineering Automation

ODOT's Move Towards...

3D Everything!



Key Concepts

- ▶ **Digital Data**
 - ▶ Spatially enabled (including non-spatial documents)
 - ▶ Reliable (quality control)
 - ▶ Readable (universal published file formats)
 - ▶ Secure (check-in, check-out, revision, privacy, security)
 - ▶ Retrievable (backed up)
 - ▶ Traceable (metadata)
 - ▶ Migrated forward (media/format obsolescence)
- ▶ **Digital Signatures**
 - ▶ Documents and data



Key Concepts

- ▶ **Structured Data Exchange**
 - ▶ Industry standards
 - ▶ XML
 - ▶ Extensible and archive-able open format
- ▶ **Engineering Data Management**
 - ▶ Engineering content management
 - ▶ Collaboration
 - ▶ File access control
 - ▶ Traceable
 - ▶ Workflow management
 - ▶ Review/Redline
 - ▶ Check-in Check-out



Key Concepts

- ▶ **Engineering Data Management** (cont'd)
 - ▶ Version control
 - ▶ Standards checking
 - ▶ Archiving
 - ▶ Geospatial search
- ▶ **Infrastructure Life Cycle Management**
 - ▶ Develop and maintain engineering data for the life cycle of all highways
- ▶ **Asset Management**
 - ▶ Collect legacy data
 - ▶ Capture engineering data as asset is created



Key Concepts

- ▶ **Post Construction Surveys**
 - ▶ Replace as-built plans
 - ▶ Complete 3D engineered model
- ▶ **Dynamic Documents**
 - ▶ GIS/Engineering data integration
 - ▶ On-demand assembly
- ▶ **Robust IT Infrastructure**
 - ▶ Super utility
 - ▶ No single point of failure could bring the system down
 - ▶ Wireless communication



Key Concepts

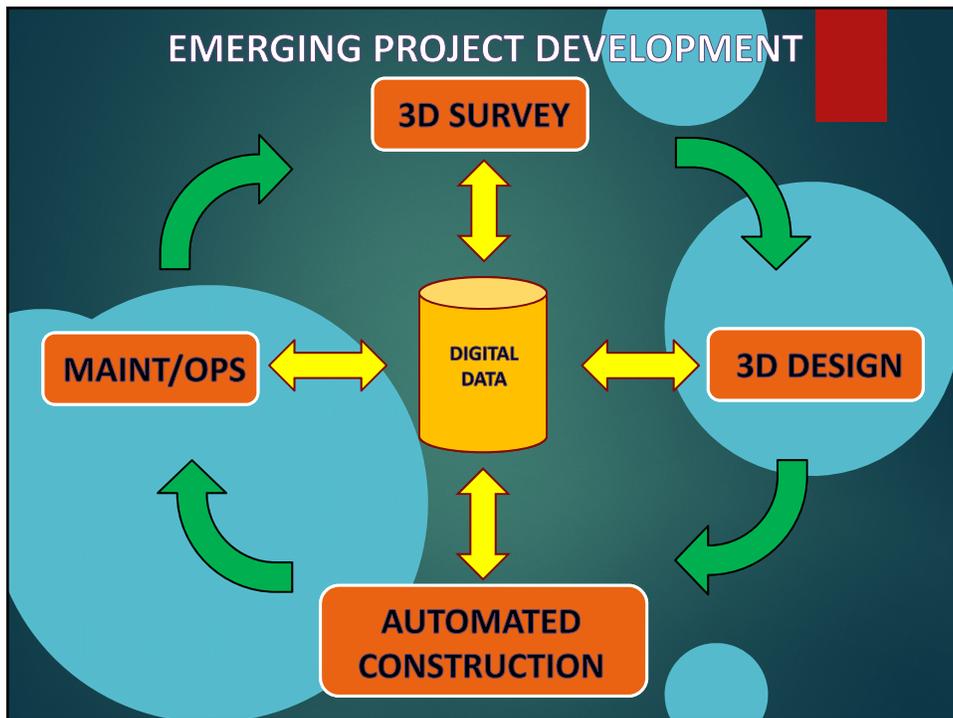
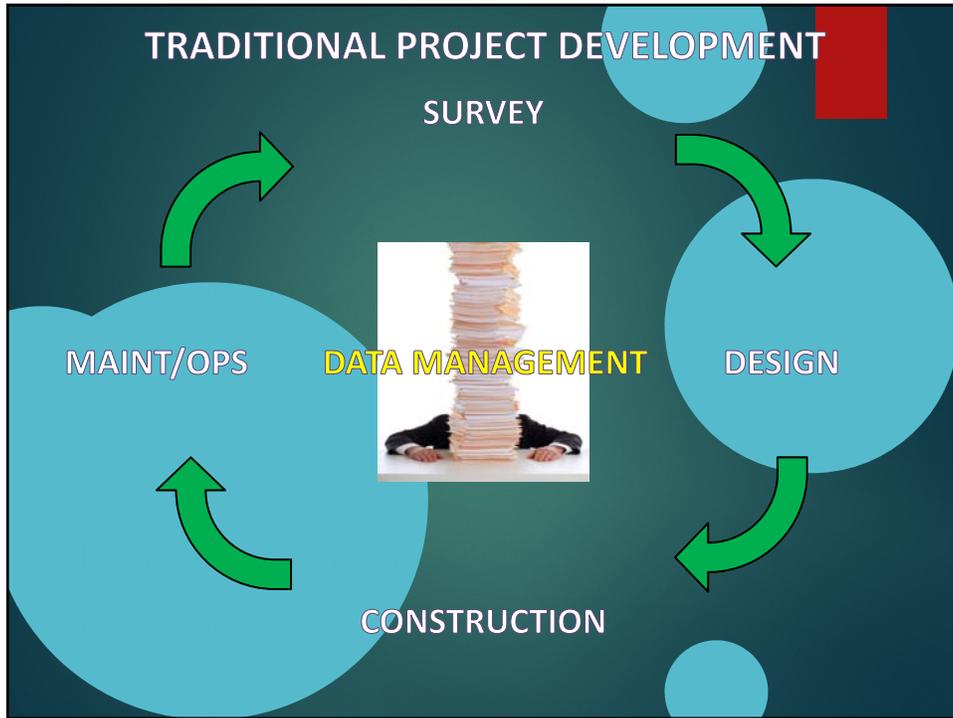
- ▶ **Real Time Networks (active control)**
 - ▶ Oregon Real-time GPS Network
- ▶ **Improved Coordinate System**
 - ▶ Low distortion projections (today)
 - ▶ Earth Centered Earth Fixed Coordinates without projections (future)
 - ▶ The Oregon Coordinate Reference System
- ▶ **3D Point Cloud Data**
 - ▶ Industry standards – ASTM E57
 - ▶ Point level metadata
 - ▶ Smart compression
 - ▶ Intelligent (classification, material, increased observables)

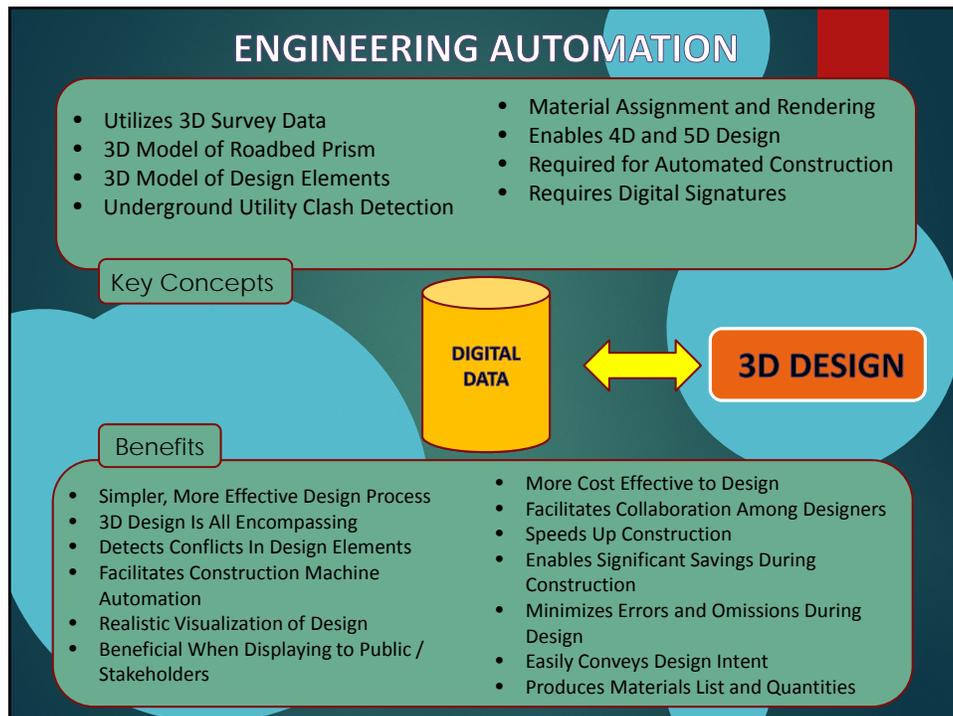
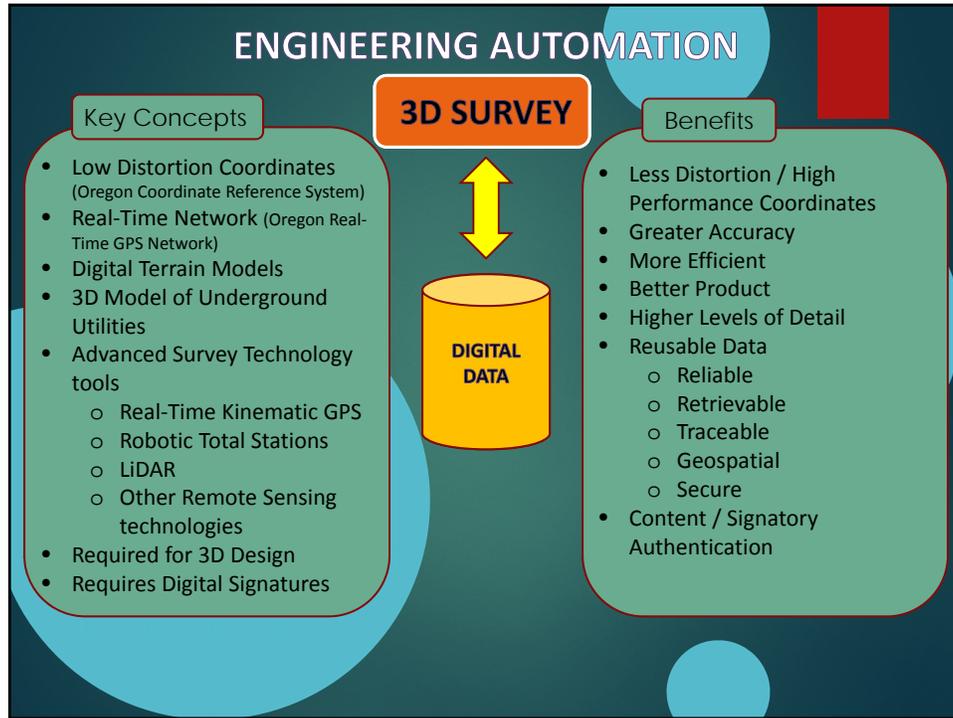


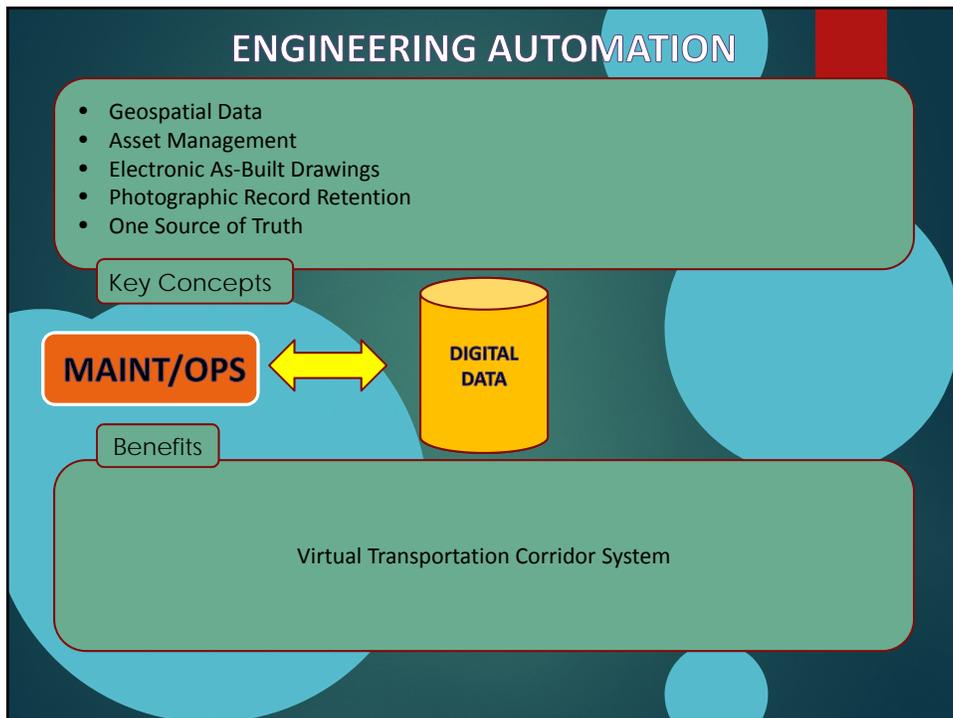
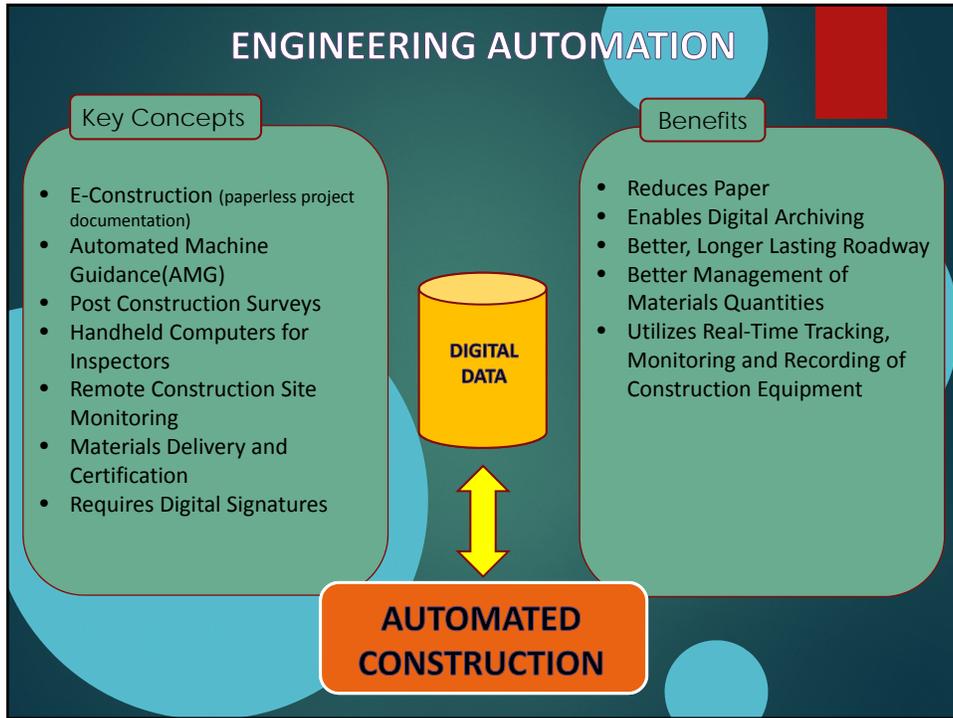
Key Concepts

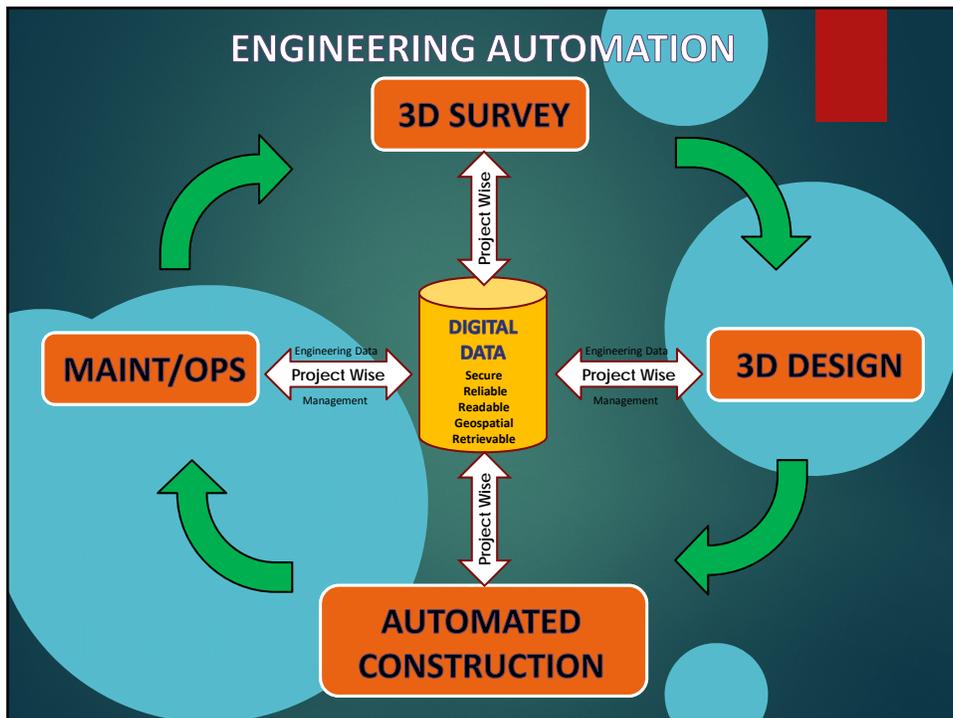
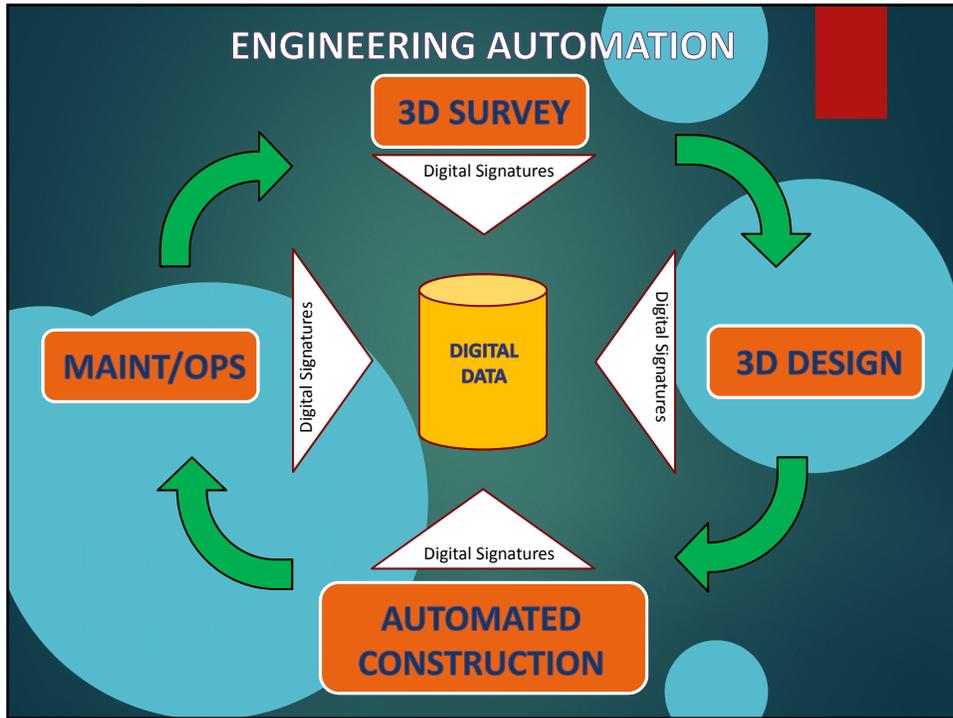
- ▶ **Underground Utility 3D Location (SUE)**
- ▶ **High Resolution (vertical and oblique) Ortho-rectified Imagery**
- ▶ **Full 3D/4D/5D Design**
- ▶ **Visualization**
- ▶ **Construction Automation**
 - ▶ Construction machine guidance and control
 - ▶ Inspection tools
 - ▶ Enhanced use of GPS (RTN, IMU)
 - ▶ Remote construction site monitoring
 - ▶ Materials delivery and certification



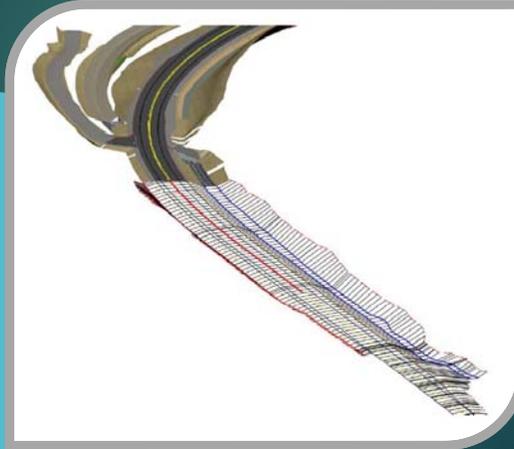








3D Design



Maps

- ❖ Purpose - Visualize a representation of a (physical) real world area
- ❖ Evolution
 - ▶ Crude sketches (2D)
 - ▶ 1:x Scale drawings (2D)
 - ▶ 1:1 Scale drawings (2D and 2 ½D)
 - ▶ True 3D (varying levels)
- ❖ Virtual world



Design Workflow - PAST

- ❖ Referenced to alignment ("P" line, etc.)
- ❖ Site represented by 2D Base Map
- ❖ Terrain represented by Cross Sections
- ❖ Grade represented by Profiles
- ❖ Blind between data points
- ❖ 2D design
- ❖ Paper plans and specifications
- ❖ Wet signatures



Design Workflow - TODAY

- ❖ Geospatially referenced
- ❖ Coordinates projected to plane
- ❖ Site represented by 2 ½ D Base Map
- ❖ Terrain represented by Digital Terrain Model (DTM)
- ❖ Blind between data points – albeit closer
- ❖ 3D roadway prism design flattened to 2D
- ❖ Paper plans and specifications
- ❖ Wet or Digital signatures



Design Workflow - FUTURE

- ❖ Geospatially referenced
- ❖ 3D coordinate system – No projections
- ❖ Site/Terrain represented by virtual world
- ❖ Full 3D design
- ❖ Digital signatures
- ❖ 3D data utilized for construction
- ❖ Hierarchy – Data primary, plans secondary



Automated Machine Guidance



Machine Guidance

A **Machine Guidance** system uses automation to provide the equipment operator a **visual indicator** of the position of the cutting edge (blade, bucket, screed, etc.) relative to the design surface being constructed.



Machine Control

A **Machine Control** system positions the cutting edge of the equipment through automation.

The system is connected to and controls the hydraulics while the operator simply drives the equipment and manages the automation.



3 Components of Machine Control

1. The design and resulting data
2. The machine w/computer, sensors, hydraulic controls, and data communication
3. The positioning system – GPS, TPS, laser, or combination



Machine Control

The ultimate system:

- ▶ No stakes required
- ▶ No grade checker required
- ▶ Records data for quality control
- ▶ Records data for volume computation
- ▶ Data could be transmitted to engineer, inspector, or surveyor for “real time” checks



Benefits (short list)

▶ Contractor

- ▶ Less Bid Risk
- ▶ Reduced Material Handling
- ▶ Less Error
- ▶ Increased Profit

▶ Oregon DOT

- ▶ Reduced Construction Costs (~ 6% FHWA estimate)
- ▶ Conveys Design Intent Better
- ▶ Better Quality (increased life expectancy)
- ▶ Reduced Construction time (~30% FHWA estimate)
- ▶ Increased Safety (workers and motorists)
- ▶ Better Material Quantity Management



ODOT's Approach into AMG

- ▶ 3D Pre-Design Survey
- ▶ 3D Design
- ▶ Digital Bid Packet
- ▶ Pre-Construction Survey
- ▶ 3D Model Provided to Contractor
- ▶ Tools for Inspectors
- ▶ Post Construction Surveys (future)
- ▶ Integration with 3D Virtual Transportation Corridor, Asset Management, and GIS (future)





GNSS
Base Station

Part of the Oregon
Real-Time GPS Network



The image shows a GNSS base station in a rural field. It consists of a white Leica antenna mounted on a metal pole, which is connected to a grey control box. The control box has its door open, revealing internal components like a battery and various cables. The background shows a field of tall grass under a cloudy sky.

GPS Guided Bull Dozer



The image shows a yellow CAT bulldozer operating in a field. The bulldozer is equipped with a large front blade and is pushing a pile of dirt. The background features a line of green trees under a clear blue sky.

GPS Guided Excavator



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GPS Guided Motor Grader



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GPS Guided Motor Grader



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3D Laser Scanner — Post Construction Survey



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Robotic Total Station



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Intelligent Compactor



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Intelligent Compactor



Robot Controlled Curb/Wall Machine



Robot Controlled Curb/Wall Machine



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Robot Guided Paver



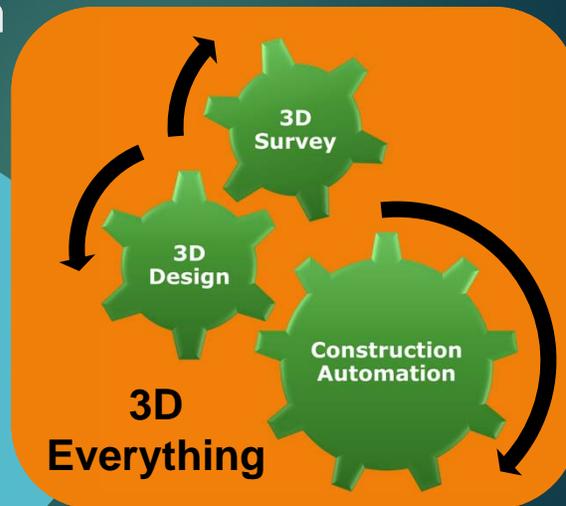
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Robot Guided Paver



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Engineering Automation Section

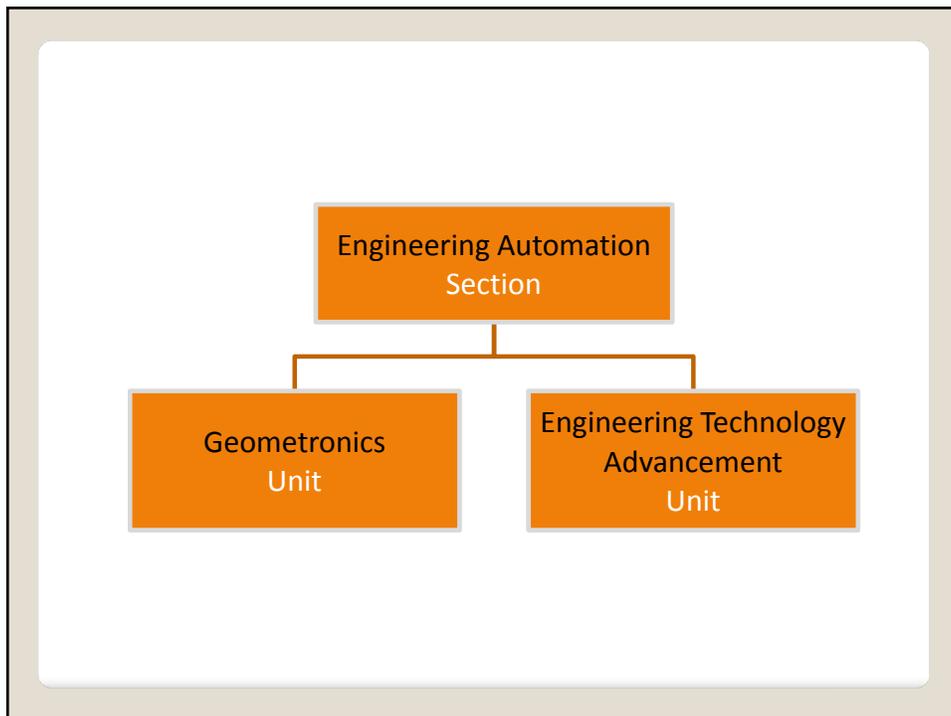


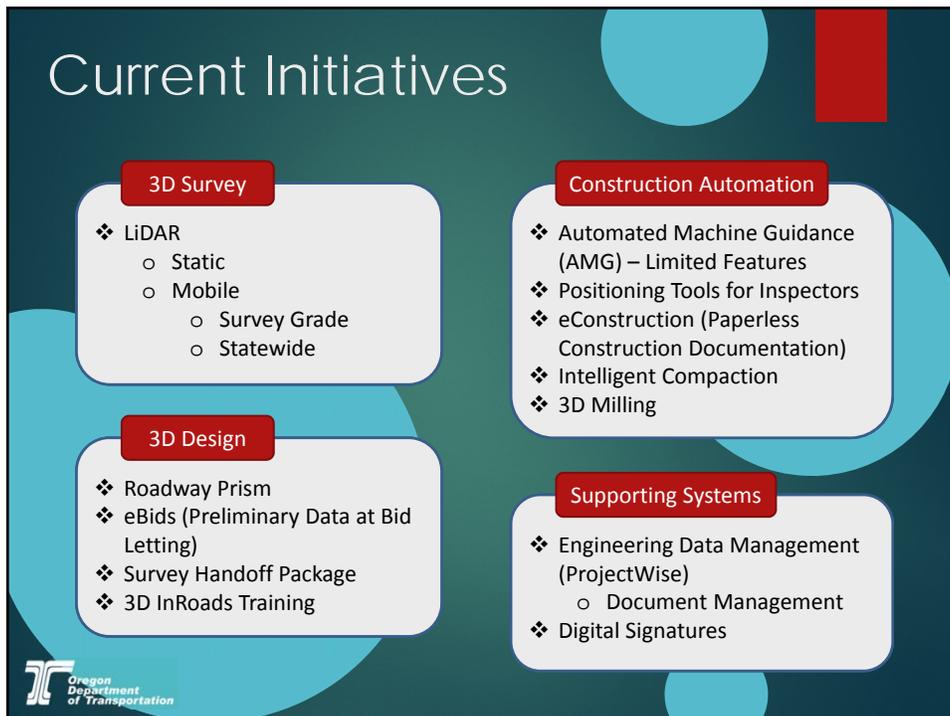
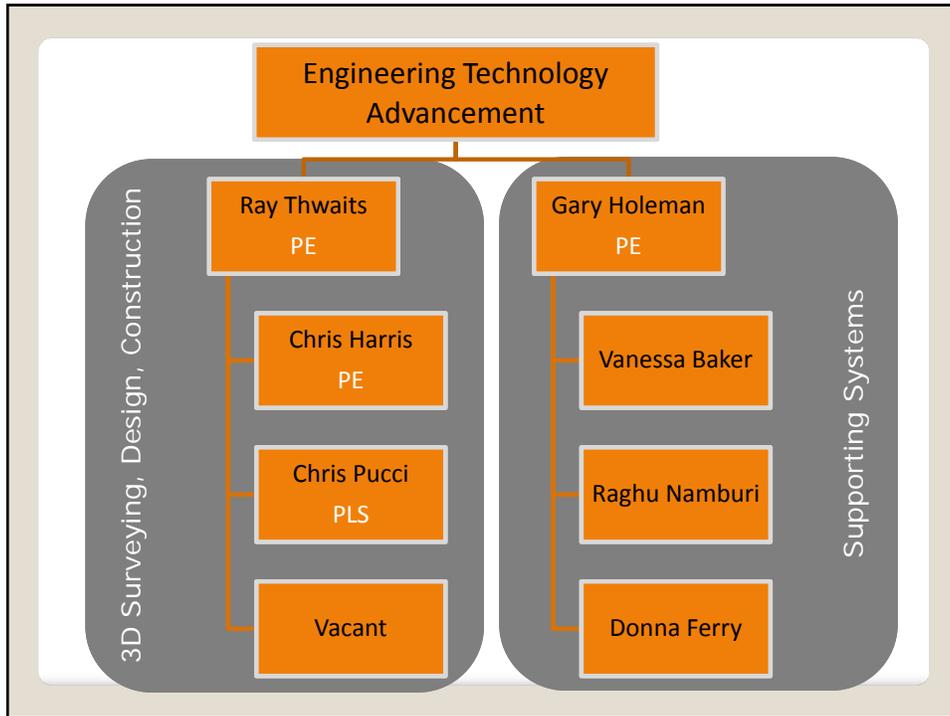
Oregon Department of Transportation

Engineering Automation Section

- ▶ **To Provide Leadership in all Aspects of Engineering Automation**
 - ▶ Survey
 - ▶ Design
 - ▶ Construction
 - ▶ Supporting Systems
- ▶ **Research New Technology**
 - ▶ Stay Informed of Industry Trends
 - ▶ Plan for the Future
- ▶ **Initiate, Develop, and Implement New Initiatives**
- ▶ **Provide Training, Technical Support and Guidance**

In Collaboration with Regions, Technical Services Sections, other ODOT Partners, FHWA, Industry, and Academia.





Near Future Initiatives

3D Survey

- ❖ Unmanned Aircraft
 - Quarry Mapping
 - Bridge Inspection
- ❖ Subsurface Utility Engineering (SUE)

Construction Automation

- ❖ Automated Machine Guidance (AMG) – More Features
- ❖ Post-Construction Surveys
- ❖ Data Integration
 - ❖ Asset Management
 - ❖ GIS/TransInfo

3D Design

- ❖ Beyond Roadway Prism
- ❖ Bridge
- ❖ Subsurface Features

Supporting Systems

- ❖ Engineering Data Management (ProjectWise)
 - Workflow Management
 - Geospatial Attributes and Search Capabilities

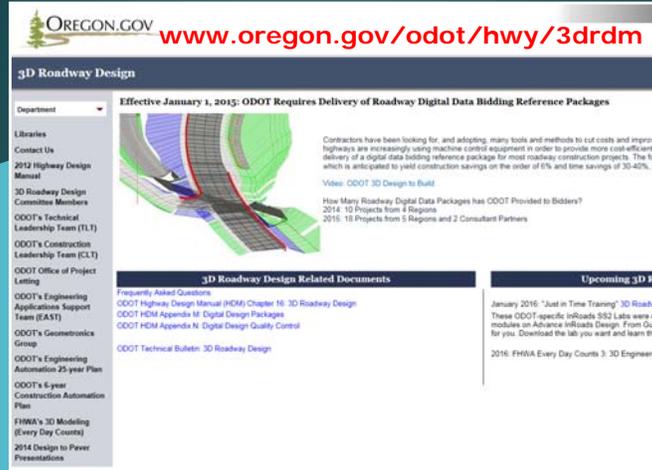


Work in Progress

DOCUMENTS, SPECIFICATIONS, TRAINING, ETC.



3D Roadway Design Web Site



3D Roadway Advanced Training

- ❖ Demonstrates the use of advanced InRoads modeling techniques that can be used in the creation of 3D engineered models
- ❖ The modules can be taken sequentially or as-needed
- ❖ Accessing the modules through iLearn.Oregon.gov will create a transcript that can be used to document PDHs.



3D Roadway Advanced Training

Title
Introduction To Use Of Training Modules/Lab Exercises
Visualization of InRoads Data
Working With InRoads Features
Rock Slope Benching Using InRoads
Overburden End Condition Using InRoads
Barriers Using InRoads
Retaining Walls Using InRoads
Abutments Using InRoads
Minor Approaches and Driveways Using InRoads
Guardrails Using InRoads
Overlay Tools and Widening Using InRoads
Modeling Gores Using InRoads
Intersection Modeling Using InRoads

www.oregon.gov/ODOT/CS/east/Pages/Training.aspx



3D Design Project Stats

2014		10 projects in 4 Regions
Contract No.	Project Name	Region
14658	OR39: MERRILL NCL - CALIFORNIA STATE LINE	4
14662	OR 42: COUNTY LINE CURVES PHASE 1	3
14671	FFO-US97@CHERRY LANE & FFO-US26@DOVER LANE MADRAS	4
14681	OR140: RITTER RD - DEER RUN RD (BLY MTN)	4
14705	OR18: NEWBERG-DUNDEE BYPASS (PHASE 1D)	2
14722	OR18: NEWBERG-DUNDEE BYPASS (PHASE 1E)	2
14742	US20 @ 8TH STREET (BEND)	4
14761	FFO-US97 @ 1ST STREET (LAPINE)	4
14766	US97-J STREET INTERSECTION (MADRAS SOUTH Y)	4
14765	I-205 AT SE STRAWBERRY LANE OVERCROSSING	1



3D Design Project Stats

2015		18 Projects in 5 Regions and 2 Consultant Partners
Contract No.	Project Name	Region
14769	JS730: POWERLINE RD INTERSECTION IMPROVEMENTS SEC.	5
14777	I-5: ANLALUF - ELKHEAD RD PAVING	3
14785	I-5: EXIT 61 (LOUISE CREEK) INTERCHANGE IMPROVEMENTS	3
14793	JS97: MORO-MADRAS SEC.	4
14804	OR62: FORT KLAMATH SIDEWALK IMPROVEMENTS	4
14803	OR224 (CLACKAMAS HWY): SE 197TH AVE	1
14810	OR140: BOWERS BRIDGE AND QUARTZ CREEK CULVERTS	4
14808	FFO-OR 138E: CORRIDOR SOLUTIONS (ROSEBURG)	3
14825	OR8: SW 185TH AVE.	1
14834	I-5: SISKIYOU REST AREA (ASHLAND)	3
14843	EMPIRE BLVD. NEWMARK AVE-WASHINGTON RD (COOS BAY)	3 (by Consultant)
14842	OR224 (CLACKAMAS HWY): SE 232ND DR SECTION	1
14851	I-5 SB: BROADWAY-WEIDLER EXIT RAMP (PORTLAND) PROJECT	1
14853	ROGUE-UMPUQUA SB: GUARDRAIL & TURNOUT IMPROVEMENTS	3
14859	LOOKINGGLASS CR RD: LOOKINGGLASS CR BR REPLACEMENT	3 (by Consultant)
14860	JS97 @ WICKIUP JCT (LA PINE) SEC.	4
14865	OR38: LUDEY CR CULVERT REPLACEMENT	3
14861	JS101 @ NE DEVILS LAKE RD	2



3D Design Project Stats

2016 (to date)		6 Projects in 3 Regions
Contract No.	Project Name	Region
14786	OR 62: CORRIDOR SOLUTIONS UNIT 2 (MEDFORD)	3 (by Consultant)
14868	OR18:NEWBERG-DUNDEE BYPASS (PH 1G)(SPRINGBROOK RD) SEC.	2
14870	OR42: GRAY CREEK CULVERT REPLACEMENT	3
14875	17TH AVE TRAIL: SE OCHOCO - SE MCLOUGHLIN	1
14872	US20 PME: ENVIRONMENTAL MITIGATION MEASURES	2
14879	OR18 @ CHRISTENSEN ROAD SECTION	2



Intelligent Compaction

❖ Rollers equipped with GNSS positioning, thermal sensing, and/or accelerometer based measurement systems for soil, aggregate and asphalt.

❖ Advantages

- ▶ Real-time monitoring of compaction efforts
- ▶ On screen visibility for night work
- ▶ Identification of weak spots, material changes
- ▶ Evaluate efficiency of paving operations (paver stops/ lay down temperature)
- ▶ Troubleshooting tool



Intelligent Compaction

❖ ODOT Pilot Projects

- ▶ 2014: 1 Project, CCO
- ▶ 2015: 3 Projects, CCO
- ▶ 2016: 3 Projects, Special Provision

❖ Developing training for PM offices

❖ Pooled Fund Study for Veta Software

- ▶ Provide input on future development of analysis software
- ▶ Collaborate with other agencies on practices and specifications



Intelligent Compaction
Users Guide



3D Milling

- ❖ Uses 3D model (line strings or surface) to adjust elevation and slope
- ❖ Accurately correct pavement cross slope without the use of an asphalt wedge



3D Milling

- ❖ Accurately construct pavement cross slope on shifted alignments
- ❖ Improve pavement smoothness
- ❖ Control PCC quantity on inlay projects
- ❖ Provide surface for uniform paving and compaction

White paper on the uses and benefits of 3D Milling



AMG Specifications

- ❖ Including reference to 3D Design Model
- ❖ Quality assurance and acceptance procedure for contractor model
- ❖ Construction tolerances
 - ▶ Proper references and unit uniformity
 - ▶ Appropriate tolerances for each construction activity
 - ▶ Separate OG DTM confidence points and construction grade checks
 - ▶ Clarify requirements for inside and outside roadway prism



Inspector Positioning Tablet

- ❖ Rugged Tablet with built in GNSS antenna +/- 2cm accuracy
- ❖ Can be used "handheld"
- ❖ Or with an external antenna and rod for higher accuracy
- ❖ Software to display and use XML files for alignment, surface and design files



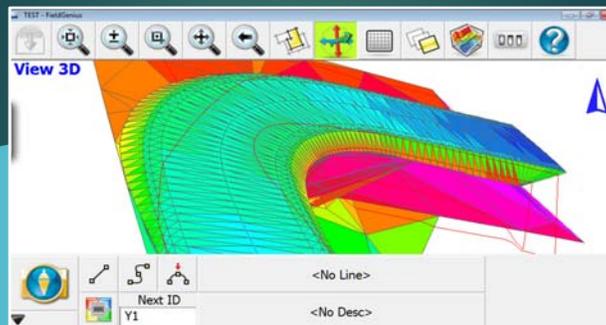
Inspector Positioning Tablet

- ▶ Rugged Outdoor Tablet
- ▶ 9 ½" x 7" x 1 ½" body
- ▶ 9" Screen
- ▶ Touchscreen
- ▶ Full computer
- ▶ Survey tool

Deployed 9 Systems
Statewide.
Evaluating Effectiveness
and Benefits.



Inspector Positioning Tablets



- ▶ FieldGenius Survey Software
- ▶ Uses XML Files Directly, No Conversion
- ▶ Full Survey Software



